
Exercises General Relativity and Cosmology

Priv.-Doz. Stefan Förste, Cesar Fierro

Hand in: 22.5.2017

Just a reminder: The solutions must be handed in in groups of two to three students.

–HOMEWORK–

1 Tangent & cotangent vectors in General Relativity (10 points)

In this part we make a comeback to part 1 of the exercise sheet 1. Now we make the application for general relativity, where the spacetime is described by a differentiable manifold M equipped with a Lorentz metric¹ g .

- a) Why can spacetime not play the role of V in general relativity? (2 points)

Instead, the tangent space $T_p M$ at the point $p \in M$ plays the role of V (pointwise). Given coordinates on a patch $U \subset M$ around p , $x^\mu : U \rightarrow \mathbb{R}^4$ with $\mu = 1, \dots, 4$, the tangent space is spanned by the partial derivatives with respect to the coordinates, i.e. $\partial_\mu = \frac{\partial}{\partial x^\mu}$. The duals of ∂_μ are denoted by dx^μ , they are elements of the cotangent space $T_p^* M$.

- b) Does μ in x^μ label a vector or dual vector component, or a set of maps? (0.5 points)

- c) What object in H 1.1 is ∂_μ associated to? (1 point)

- d) Express $\partial'_\mu = \frac{\partial}{\partial y^\mu}$ in terms of the ∂_μ . (2 points)

- e) In item b) of H 1.1 we have looked at a change of basis. What is the analog to this here: The change from x^μ to y^μ or from ∂_μ to ∂'_μ ? (1 point)

- f) Express dy^μ (the dual of ∂'_μ) in terms of the dx^μ . (1 point)

We have stated above, that $T_p M$ plays the role of V . This means that V now depends on the point in spacetime, thus it is natural to consider tensor fields,

$$\mathcal{T}^{k,l} : M \rightarrow T^{k,l}. \quad (1)$$

A tensor field of (k, l) type assigns a (k, l) -tensor to each point in spacetime.

- g) Let the components of a (k, l) -tensor T associated to the basis $\{\partial_\mu\}$ of $T_p M$ be $T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l}$. What would be the components of T in a basis $\{\partial'_\mu\}$? (1 point)

In particular, at a given $p \in M$ the Lorentz metric $g_p : T_p M \times T_p M \rightarrow \mathbb{R}$ is a type (0,2) which satisfies the following axioms at each point $p \in M$:

¹Its definition is given below.

- $g_p(U, V) = g_p(V, U)$,
 - if $g_p(U, V) = 0$ for any $U \in T_p M$, then $V = 0$,
 - one of the eigenvalues of the matrix form of $(g_{\mu\nu}(p))$ in $g_p = g_{\mu\nu}(p) dx^\mu \otimes dx^\nu$ is negative, the rest are positive.
 - The map $p \mapsto g_p$ is smooth.
- h) According to H1.1, what object is associated to g_p ? What is $g_{\mu\nu}(p)$ in this case? (1 point)
- i) What would be the physical meaning associated to the third axiom for a Lorentz metric? (0.5 points)

If g is a Lorentz metric, (M, g) is called a Lorentz manifold. For such a case, the elements of $T_p M$ are divided into three classes:

- $g_p(U, U) > 0 \Rightarrow U$ is spacelike,
- $g_p(U, U) = 0 \Rightarrow U$ is lightlike,
- $g_p(U, U) < 0 \Rightarrow U$ is timelike.

2 Pullbacks & Pushforwards (13 points)

In local coordinates $\{y^\alpha\}$ on N the metric tensor can be expanded as

$$g = g_{\alpha\beta} dy^\alpha \otimes dy^\beta \quad (2)$$

in terms of smooth functions $g_{\alpha\beta}$. Examples are \mathbb{R}^n equipped with the standard euclidean metric, which is just what we call \mathbb{R}^n , or \mathbb{R}^n equipped with the Minkowski metric, which is n -dimensional Minkowski space $\mathbb{R}^{1,n-1}$. This also shows that one and the same manifold can be equipped with different metrics, by which it is made into different objects. Consider a manifold N equipped with a metric g and a second manifold M with local coordinates $\{x^\mu\}$. If we further have a smooth map $\varphi : M \rightarrow N$ we can use this map induce a metric for M . For that we need to introduce a couple of new concepts:

The tangent bundle TM of a manifold M assembles all tangent vectors in M , it is defined as

$$TM = \bigcup_{p \in M} \{p\} \times T_p M = \{(p, v) : p \in M, v \in T_p M\}. \quad (3)$$

The map φ also induces a natural map $\varphi_* : TM \rightarrow TN$ called the *pushforward* of φ , which makes the following diagram commute

$$\begin{array}{ccc} TM & \xrightarrow{\varphi_*} & TN \\ \downarrow \pi & & \downarrow \pi \\ M & \xrightarrow{\varphi} & N \end{array}, \quad \text{i.e. } \pi \circ \varphi_* = \varphi \circ \pi.$$

Here $\pi(p, v) = p$. Let $V \in T_p M$. Then the action of φ_* on V will be given by

$$\varphi_* V = \frac{\partial y^\alpha}{\partial x^\mu} V^\mu \frac{\partial}{\partial y^\alpha} \Big|_{\varphi(p)}. \quad (4)$$

Another important concept is that of the *pullback*, for a tensor field $A \in \mathcal{T}^{0,l}$ the pullback $\varphi^* A$ is given by

$$\varphi^* A(p)(V_1, \dots, V_l) = A(\varphi(p))(\varphi_* V_1, \dots, \varphi_* V_l). \quad (5)$$

This gives the so called *induced metric* on M , which is denoted as $\varphi^* g$. With g as in eq. (2), the induced metric locally reads

$$\varphi^* g = \left[g_{\alpha\beta} \left(\frac{\partial y^\alpha}{\partial x^\mu} \right) \left(\frac{\partial y^\beta}{\partial x^\nu} \right) \right] dx^\mu \otimes dx^\nu. \quad (6)$$

- a) Use the pushforward φ_* action in (4) to derive (6). (1 point)

Consider the two-sphere S^2 embedded in \mathbb{R}^3 ,

$$S^2 = \{R(\cos \phi \sin \theta, \sin \phi \sin \theta, \cos \theta) \mid \phi \in [0, 2\pi), \theta \in [0, \pi), R > 0\}. \quad (7)$$

- b) How do you need to restrict the domain of θ and ϕ so that the spherical coordinates

$$\varphi_s^{-1}(\phi, \theta) : \begin{pmatrix} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{pmatrix} \mapsto \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \quad (8)$$

provide a chart on the sphere?

(1 point)

Let ι be the inclusion map

$$\begin{aligned} \iota : S^2 &\longrightarrow \mathbb{R}^3 \\ (\theta, \phi) &\longmapsto R(\cos \phi \sin \theta, \sin \phi \sin \theta, \cos \theta) \end{aligned} \quad (9)$$

- c) Consider the following points $\{(0, 0), (\pi, 0), (0, \pi/2)\} \in S^2$. Let $X_\theta = \partial_\theta$, $X_\phi = \partial_\phi$. What would be the pushforward $\iota_* X_\theta(p)$ and $\iota_* X_\phi(p)$ for each of these points? (1 point)
- d) Calculate the induced metric on S^2 . (3 points)

Now consider the two-dimensional torus given by its embedding in \mathbb{R}^3 ,

$$T^2 = \{((R + r \cos \theta) \cos \phi, (R + r \cos \theta) \sin \phi, r \sin \theta) \mid \theta, \phi \in [0, 2\pi), R > r > 0\}. \quad (10)$$

- e) The embedding of T^2 in \mathbb{R}^3 is given in eq. (10). Use the corresponding inclusion map to calculate the induced metric on T^2 . (3 points)
- f) In cosmology the so called *de Sitter space* will be of importance. This space is cut out of five-dimensional Minkowski space $\mathbb{R}^{1,4}$ — with coordinates u, w, x, y, z , with u being timelike — by the hyperboloid equation

$$-u^2 + w^2 + x^2 + y^2 + z^2 = \alpha^2, \quad \alpha \in \mathbb{R}. \quad (11)$$

On de Sitter space we introduce coordinates t, χ, θ, ϕ and embed it in $\mathbb{R}^{1,4}$ by

$$\begin{aligned} u &= \alpha \sinh(t/\alpha), & w &= \alpha \cosh(t/\alpha) \cos \chi, & x &= \alpha \cosh(t/\alpha) \sin \chi \cos \theta \\ y &= \alpha \cosh(t/\alpha) \sin \chi \sin \theta \cos \phi, & z &= \alpha \cosh(t/\alpha) \sin \chi \sin \theta \sin \phi. \end{aligned} \quad (12)$$

Calculate the induced metric on de Sitter space.

(4 points)

3 Vector fields & tensor acrobatics (15 pts.)

A smooth vector field X on a manifold M fulfills the two conditions

$$\begin{aligned} \text{Linearity:} \quad X(\alpha f + \beta g) &= \alpha X(f) + \beta X(g) & \text{with } \alpha, \beta \in \mathbb{R}, f, g \in C^\infty(M) \\ \text{Leibniz rule:} \quad X(f \cdot g) &= f \cdot X(g) + g \cdot X(f) & \text{with } f, g \in C^\infty(M). \end{aligned} \quad (13)$$

In general, maps with the properties (13) are called *derivations*. Given two vector fields X and Y we define a new vector field $[X, Y]$, the *Lie bracket* or *commutator* of X and Y , by

$$[X, Y](f) = X(Y(f)) - Y(X(f)) \quad \text{for } f \in C^\infty(M). \quad (14)$$

- a) Show in two ways that $[X, Y]$ is indeed a vector field:
- Prove that $[X, Y]$ is a derivation. (3 points)
 - Write $[X, Y]$ in terms of components and show that they transform as those of a vector field under change of coordinates. (2 points)

Note that neither XY nor YX is a vector field.

- b) Show that the Lie bracket is
- skew-symmetric, $[X, Y] = -[Y, X]$, and (1 point)
 - satisfies the Jacobi identity, $[[X, Y], Z] + [[Z, X], Y] + [[Y, Z], X] = 0$. (2 points)
- c) Consider \mathbb{R}^2 equipped with some coordinates x^1, x^2 . Calculate the Lie bracket of the coordinate vector fields $\partial_1 = \frac{\partial}{\partial x^1}$ and $\partial_2 = \frac{\partial}{\partial x^2}$. (1 point)
- d) Find an example of two nowhere-vanishing, (at each point) linearly independent vector fields in \mathbb{R}^2 whose Lie bracket does not vanish. Note that these two vector fields provide a basis for the tangent space at each point. Due to your findings in item c) they can, however, not be coordinate vector fields. (3 points)

Let $T \in T^{0,k}(V)$ in a given vector space V . We denote $\text{Sym}(T)$ as the symmetrized form of T , where its components are given by

$$\text{Sym}(T)_{\mu_1, \dots, \mu_k} = T_{(\mu_1, \dots, \mu_k)} = \frac{1}{k!} \sum_{\sigma \in S_k} T_{\mu_{\sigma(1)}, \dots, \mu_{\sigma(k)}}. \quad (15)$$

Similarly, we define the fully antisymmetrized form of T as the tensor $\text{Alt}(T)$ such that

$$\text{Alt}(T)_{\mu_1, \dots, \mu_k} = T_{[\mu_1, \dots, \mu_k]} = \frac{1}{k!} \sum_{\sigma \in S_k} \text{sgn} \sigma \cdot T_{\mu_{\sigma(1)}, \dots, \mu_{\sigma(k)}}. \quad (16)$$

We can make an analogous definition for tensors in $T^{l,0}(V)$ by raising all of the indices in (15) and (16).

- For a $T \in T^{0,2}(V)$, show that $T = \text{Sym}(T) + \text{Alt}(T)$. (1 point)
- Why is that for $T \in T^{0,3}(V)$, $T \neq \text{Sym}(T) + \text{Alt}(T)$? (0.5 points)
- Prove for $X \in T^{2,0}(V)$ and $Y \in T^{0,2}(V)$ the following: (1.5 points)
 - $X^{(\mu\nu)}Y_{\mu\nu} = X^{(\mu\nu)}Y_{(\mu\nu)}$,
 - $X^{[\mu\nu]}Y_{\mu\nu} = X^{[\mu\nu]}Y_{[\mu\nu]}$,
 - $X^{[\mu\nu]}Y_{(\mu\nu)} = 0$.